

## Multi-purpose Intelligent Robot

# FANUC Robot R-2000iB series



The FANUC robot R-2000iB is the intelligent robot for versatile applications with the up to date expertise in our quarter century at FANUC. The highly reliable robot with intelligence and network collaboration provides the best cost performance and prompts ease of use applications with integrated versatile process solutions such as spot welding, handling, assembling and so on.

### Simple and compact mechanical unit

R-2000iB provides the ultimate slim and compact body with the simplified vertical articulated arm, while maintaining the largest motion area and the heaviest payload in the class.

- Compact wrist unit
- Minimum interference at rear side
- Dense installation of multi robot

### Intelligence and networking

Newly developed robot controller by enhanced CPU performance includes the latest software function, provides the most up to date intelligent and networking features.

- Higher motion performance
- Integrated vision
- Bin picking function
- Diagnostics function

### Application system



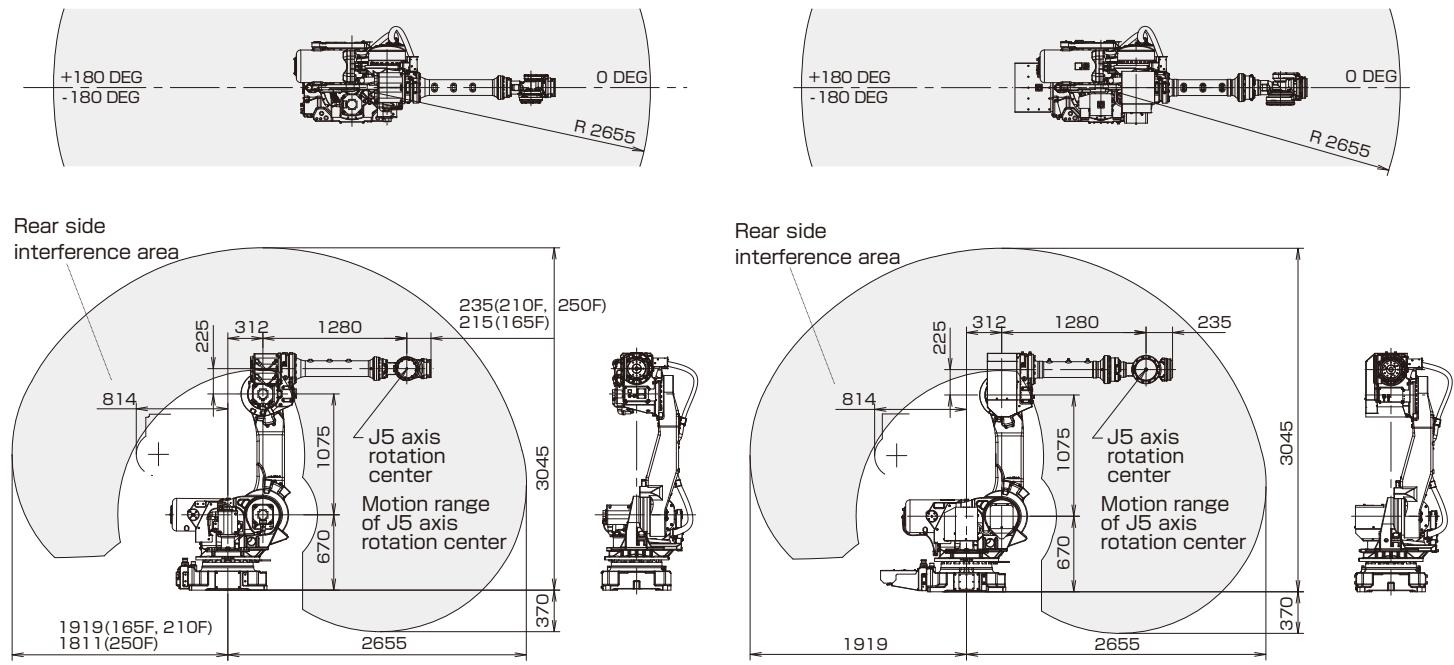
Handling of scattered workpieces



Spot welding by synchronized 2 robots

# FANUC Robot R-2000iB/165F, 210F, 250F, 210WE

Operating space (R-2000iB/165F, 210F, 250F) Operating space (R-2000iB/210WE)



## Specifications

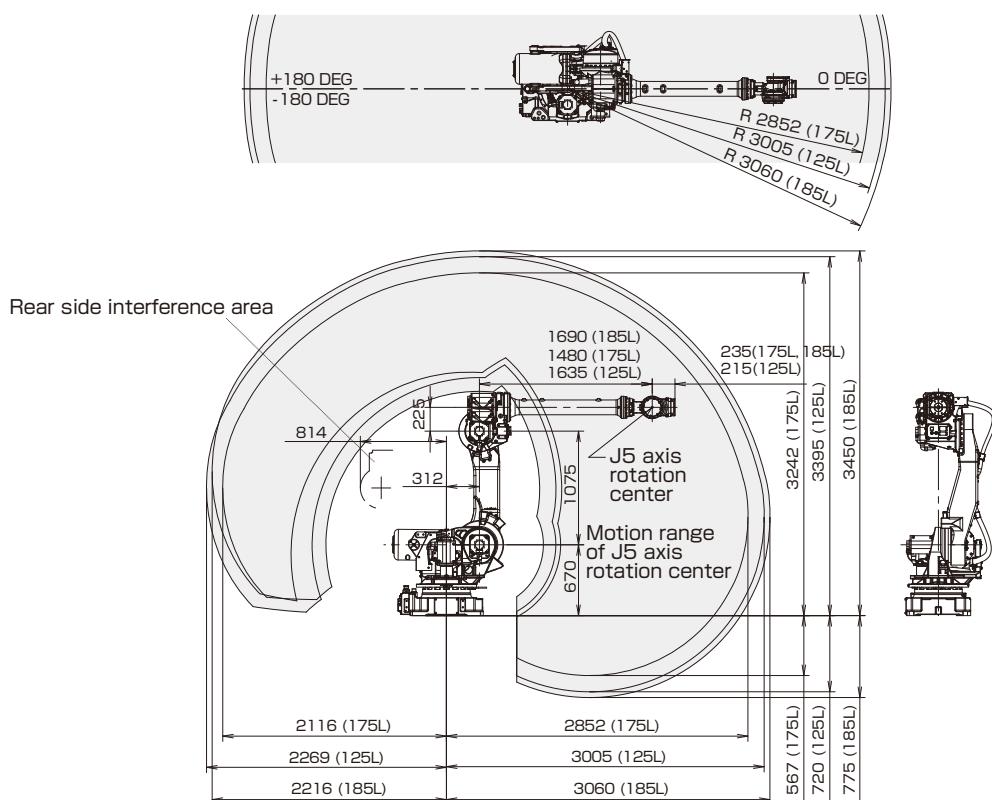
Item	Specifications				
	R-2000iB/165F	R-2000iB/210F	R-2000iB/250F	R-2000iB/210WE	
Type	Articulated type				
Controlled axes	6 axes (J1, J2, J3, J4, J5, J6)				
Reach	2655mm	2655mm	2655mm	2655mm	
Installation	Floor				
Motion range (Maximum speed) Note 1)	J1 axis rotation	360° (110°/s) 6.28rad (1.92rad/s)	360° (95°/s) 6.28rad (1.66rad/s)	360° (95°/s) 6.28rad (1.66rad/s)	360° (95°/s) 6.28rad (1.66rad/s)
	J2 axis rotation	136° (110°/s) 2.37rad (1.92rad/s)	136° (90°/s) 2.37rad (1.57rad/s)	136° (85°/s) 2.37rad (1.48rad/s)	136° (90°/s) 2.37rad (1.57rad/s)
	J3 axis rotation	362° (110°/s) 6.32rad (1.92rad/s)	362° (95°/s) 6.32rad (1.66rad/s)	357° (88°/s) 6.23rad (1.54rad/s)	362° (95°/s) 6.32rad (1.66rad/s)
	J4 axis wrist rotation	720° (150°/s) 12.57rad (2.62rad/s)	720° (120°/s) 12.57rad (2.09rad/s)	720° (120°/s) 12.57rad (2.09rad/s)	720° (120°/s) 12.57rad (2.09rad/s)
	J5 axis wrist swing	250° (150°/s) 4.36rad (2.62rad/s)	250° (120°/s) 4.36rad (2.09rad/s)	250° (120°/s) 4.36rad (2.09rad/s)	250° (120°/s) 4.36rad (2.09rad/s)
	J6 axis wrist rotation	720° (220°/s) 12.57rad (3.84rad/s)	720° (190°/s) 12.57rad (3.32rad/s)	720° (190°/s) 12.57rad (3.32rad/s)	720° (190°/s) 12.57rad (3.32rad/s)
	Max load capacity at wrist	165kg	210kg	250kg	210kg
Max load capacity at J2 base	550kg	550kg	550kg	550kg	
Max load capacity on J3 arm	25kg	25kg	25kg	25kg	
Allowable load moment at wrist	J4 axis	921N · m 94kgf · m	1333N · m 136kgf · m	1382N · m 141kgf · m	1333N · m 136kgf · m
	J5 axis	921N · m 94kgf · m	1333N · m 136kgf · m	1382N · m 141kgf · m	1333N · m 136kgf · m
	J6 axis	461N · m 47kgf · m	706N · m 72kgf · m	715N · m 73kgf · m	706N · m 72kgf · m
Allowable load inertia at wrist	J4 axis	78.4kg · m² 800kgf · cm · s²	141.1kg · m² 1440kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²	141.1kg · m² 1440kgf · cm · s²
	J5 axis	78.4kg · m² 800kgf · cm · s²	141.1kg · m² 1440kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²	141.1kg · m² 1440kgf · cm · s²
	J6 axis	40.2kg · m² 410kgf · cm · s²	78.4kg · m² 800kgf · cm · s²	196kg · m² 2000kgf · cm · s²	78.4kg · m² 800kgf · cm · s²
Drive method	Electric servo drive by AC servo motor				
Repeatability	±0.2mm	±0.3mm	±0.3mm	±0.3mm	
Mass Note 2)	1170kg	1240kg	1270kg	1280kg	
Installation environment	Ambient temperature : 0~45° C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration : 4.9m/s²(0.5G) or less				

Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.

Note 2) Without controller.

# FANUC Robot R-2000iB /125L, 175L, 185L

## Operating space (R-2000iB/125L, 175L, 185L)



## Specifications

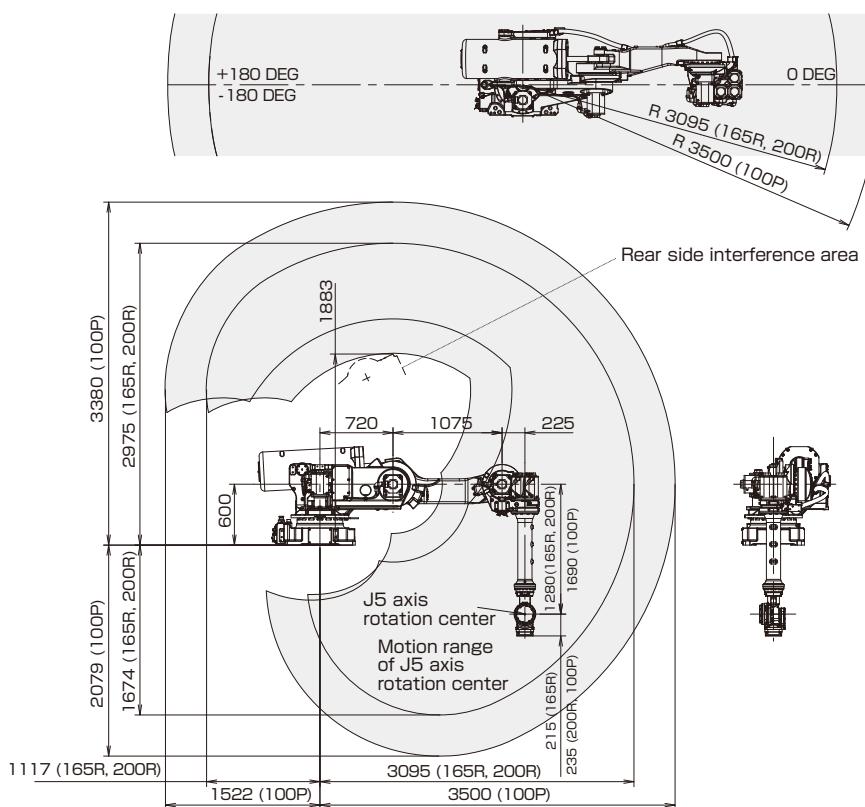
Item	Specifications		
	R-2000iB/125L	R-2000iB/175L	R-2000iB/185L
Type		Articulated type	
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)	
Reach	3005mm	2852mm	3060mm
Installation		Floor	
Motion range (Maximum speed) Note 1)	J1 axis rotation 360° (110°/s) 6.28rad (1.92rad/s)	360° (95°/s) 6.28rad (1.66rad/s)	360° (95°/s) 6.28rad (1.66rad/s)
	J2 axis rotation 136° (110°/s) 2.37rad (1.92rad/s)	136° (90°/s) 2.37rad (1.57rad/s)	136° (85°/s) 2.37rad (1.48rad/s)
	J3 axis rotation 352.6° (110°/s) 6.15rad (1.92rad/s)	356.1° (95°/s) 6.21rad (1.66rad/s)	346° (88°/s) 6.04rad (1.54rad/s)
	J4 axis wrist rotation 720° (170°/s) 12.57rad (2.97rad/s)	720° (120°/s) 12.57rad (2.09rad/s)	720° (120°/s) 12.57rad (2.09rad/s)
	J5 axis wrist swing 250° (170°/s) 4.36rad (2.97rad/s)	250° (120°/s) 4.36rad (2.09rad/s)	250° (120°/s) 4.36rad (2.09rad/s)
	J6 axis wrist rotation 720° (260°/s) 12.57rad (4.54rad/s)	720° (190°/s) 12.57rad (3.32rad/s)	720° (190°/s) 12.57rad (3.32rad/s)
Max load capacity at wrist	125kg	175kg	185kg
Max load capacity at J2 base	550kg	550kg	550kg
Max load capacity on J3 arm	20kg	20kg	—
Allowable load moment at wrist	J4 axis 588N · m 60kgf · m	1225N · m 125kgf · m	1225N · m 125kgf · m
	J5 axis 588N · m 60kgf · m	1225N · m 125kgf · m	1225N · m 125kgf · m
	J6 axis 343N · m 35kgf · m	706N · m 72kgf · m	706N · m 72kgf · m
Allowable load inertia at wrist	J4 axis 58.8kg · m² 600kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²
	J5 axis 58.8kg · m² 600kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²
	J6 axis 22.5kg · m² 230kgf · cm · s²	196kg · m² 2000kgf · cm · s²	196kg · m² 2000kgf · cm · s²
Drive method	Electric servo drive by AC servo motor		
Repeatability	±0.2mm	±0.3mm	±0.3mm
Mass Note 2)	1190kg	1260kg	1290kg
Installation environment	Ambient temperature : 0~45° C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration : 4.9m/s²(0.5G) or less		

Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.

Note 2) Without controller.

# FANUC Robot R-2000iB/165R, 200R, 100P

## Operating space (R-2000iB/165R, 200R, 100P)



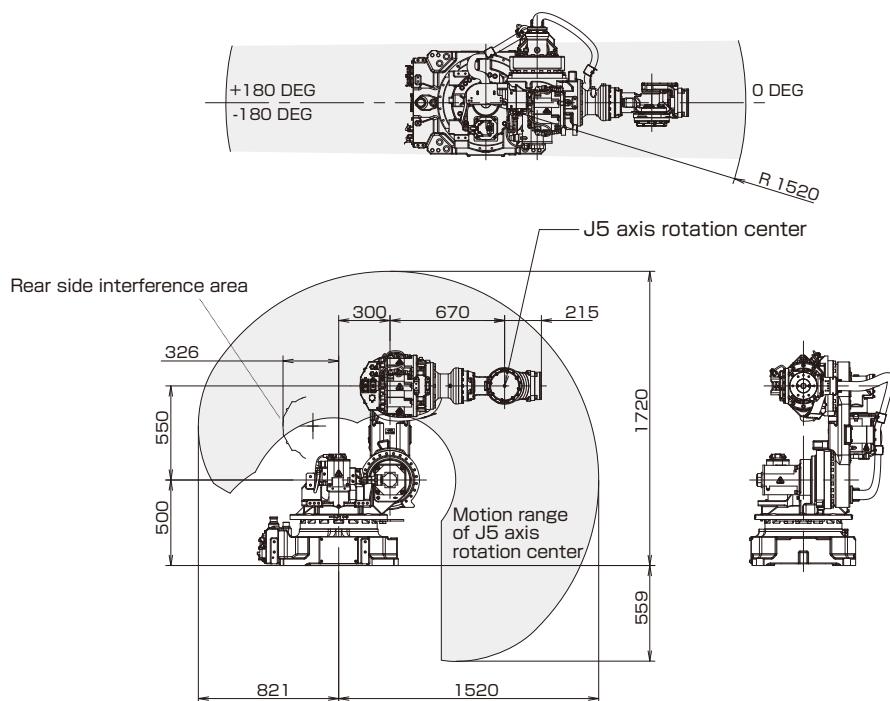
## Specifications

Item		Specifications		
		R-2000iB/165R	R-2000iB/200R	R-2000iB/100P
Type		Articulated type		
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)		
Reach		3095mm	3095mm	3500mm
Installation		Rack mount		
Motion range (Maximum speed) Note 1)	J1 axis rotation	360° (110°/s) 6.28rad (1.92rad/s)	360° (90°/s) 6.28rad (1.57rad/s)	360° (110°/s) 6.28rad (1.92rad/s)
	J2 axis rotation	185° (100°/s) 3.23rad (1.75rad/s)	185° (85°/s) 3.23rad (1.48rad/s)	185° (90°/s) 3.23rad (1.57rad/s)
	J3 axis rotation	365° (110°/s) 6.37rad (1.92rad/s)	365° (95°/s) 6.37rad (1.66rad/s)	365° (110°/s) 6.37rad (1.92rad/s)
	J4 axis wrist rotation	720° (150°/s) 12.57rad (2.62rad/s)	720° (120°/s) 12.57rad (2.09rad/s)	720° (120°/s) 12.57rad (2.09rad/s)
	J5 axis wrist swing	250° (150°/s) 4.36rad (2.62rad/s)	250° (120°/s) 4.36rad (2.09rad/s)	250° (120°/s) 4.36rad (2.09rad/s)
	J6 axis wrist rotation	720° (220°/s) 12.57rad (3.84rad/s)	720° (190°/s) 12.57rad (3.32rad/s)	720° (190°/s) 12.57rad (3.32rad/s)
	Max load capacity at wrist	165kg	200kg	100kg
Allowable load moment at wrist		550kg	550kg	550kg
Max load capacity on J3 casing		25kg	—	25kg
Allowable load inertia at wrist	J4 axis	921N · m 94kgf · m	1333N · m 136kgf · m	980N · m 100kgf · m
	J5 axis	921N · m 94kgf · m	1333N · m 136kgf · m	980N · m 100kgf · m
	J6 axis	461N · m 47kgf · m	706N · m 72kgf · m	706N · m 72kgf · m
Allowable load inertia at wrist	J4 axis	78.4kg · m² 800kgf · cm · s²	141.1kg · m² 1440kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²
	J5 axis	78.4kg · m² 800kgf · cm · s²	141.1kg · m² 1440kgf · cm · s²	225.4kg · m² 2300kgf · cm · s²
	J6 axis	40.2kg · m² 410kgf · cm · s²	78.4kg · m² 800kgf · cm · s²	196kg · m² 2000kgf · cm · s²
Drive method		Electric servo drive by AC servo motor		
Repeatability		±0.3mm	±0.3mm	±0.3mm
Mass Note 2)		1480kg	1540kg	1560kg
Installation environment		Ambient temperature : 0~45° C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration : 4.9m/s²(0.5G) or less		

Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.  
Note 2) Without controller.

# FANUC Robot R-2000iB/170CF

## Operating space (R-2000iB/170CF)



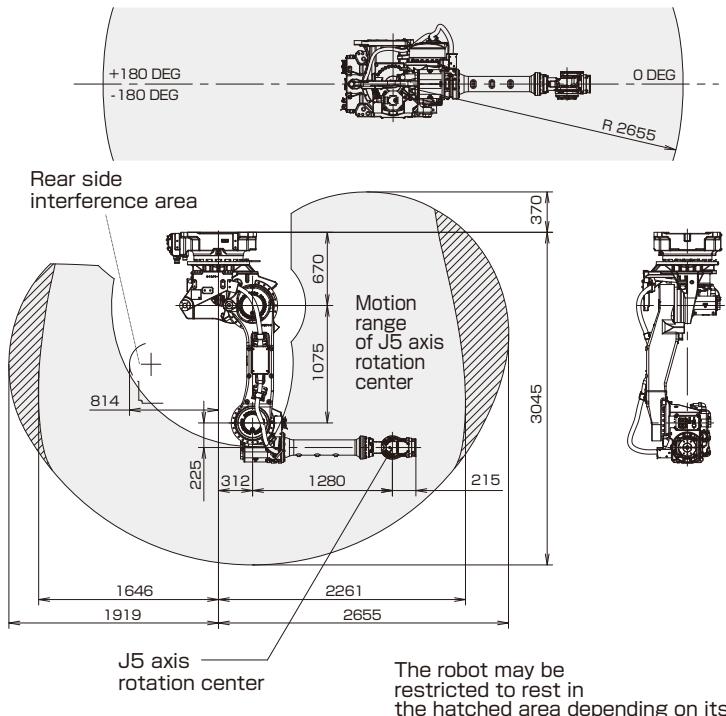
## Specifications

Item		Specifications	
		R-2000iB/170CF	
Type		Articulated type	
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)	
Reach		1520mm	
Installation		Floor, Upside-down	
Motion range (Maximum speed) Note 1)	J1 axis rotation	360° (110°/s) 6.28rad (1.92rad/s)	
	J2 axis rotation	190° (110°/s) 3.32rad (1.92rad/s)	
	J3 axis rotation	332° (110°/s) 5.79rad (1.92rad/s)	
	J4 axis wrist rotation	720° (150°/s) 12.57rad (2.62rad/s)	
	J5 axis wrist swing	250° (150°/s) 4.36rad (2.62rad/s)	
	J6 axis wrist rotation	720° (220°/s) 12.57rad (3.84rad/s)	
	Max load capacity at wrist	170kg	
Max load capacity at J2 base		550kg (Floor mount only)	
Max load capacity on J3 casing		25kg	
Allowable load moment at wrist	J4 axis	921N · m 94kgf · m	
	J5 axis	921N · m 94kgf · m	
	J6 axis	461N · m 47kgf · m	
Allowable load inertia at wrist	J4 axis	78.4kg · m² 800kgf · cm · s²	
	J5 axis	78.4kg · m² 800kgf · cm · s²	
	J6 axis	40.2kg · m² 410kgf · cm · s²	
Drive method		Electric servo drive by AC servo motor	
Repeatability		±0.15mm	
Mass Note 2)	800kg		
Installation environment		Ambient temperature : 0~45° C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration : 4.9m/s²(0.5G) or less	

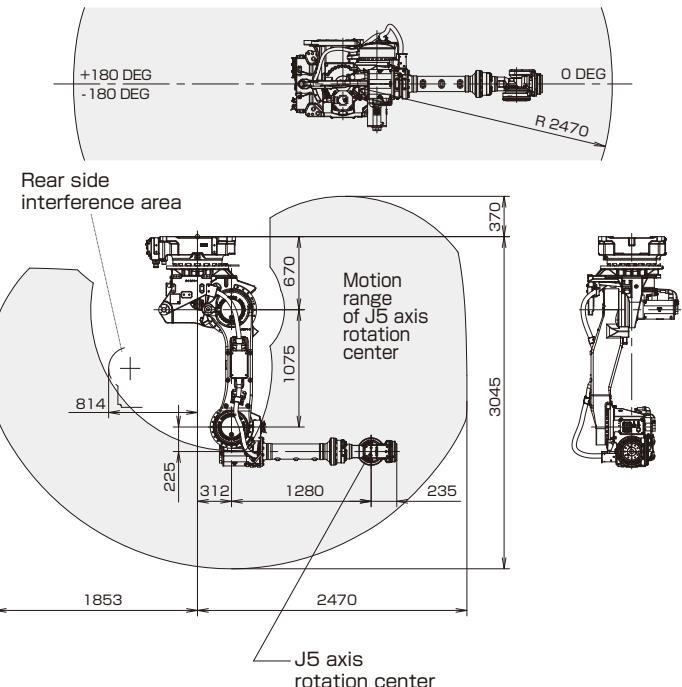
Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.  
 Note 2) Without controller.

# FANUC Robot R-2000iB/150U, 220U

Operating space (R-2000iB/150U)



Operating space (R-2000iB/220U)



## Specifications

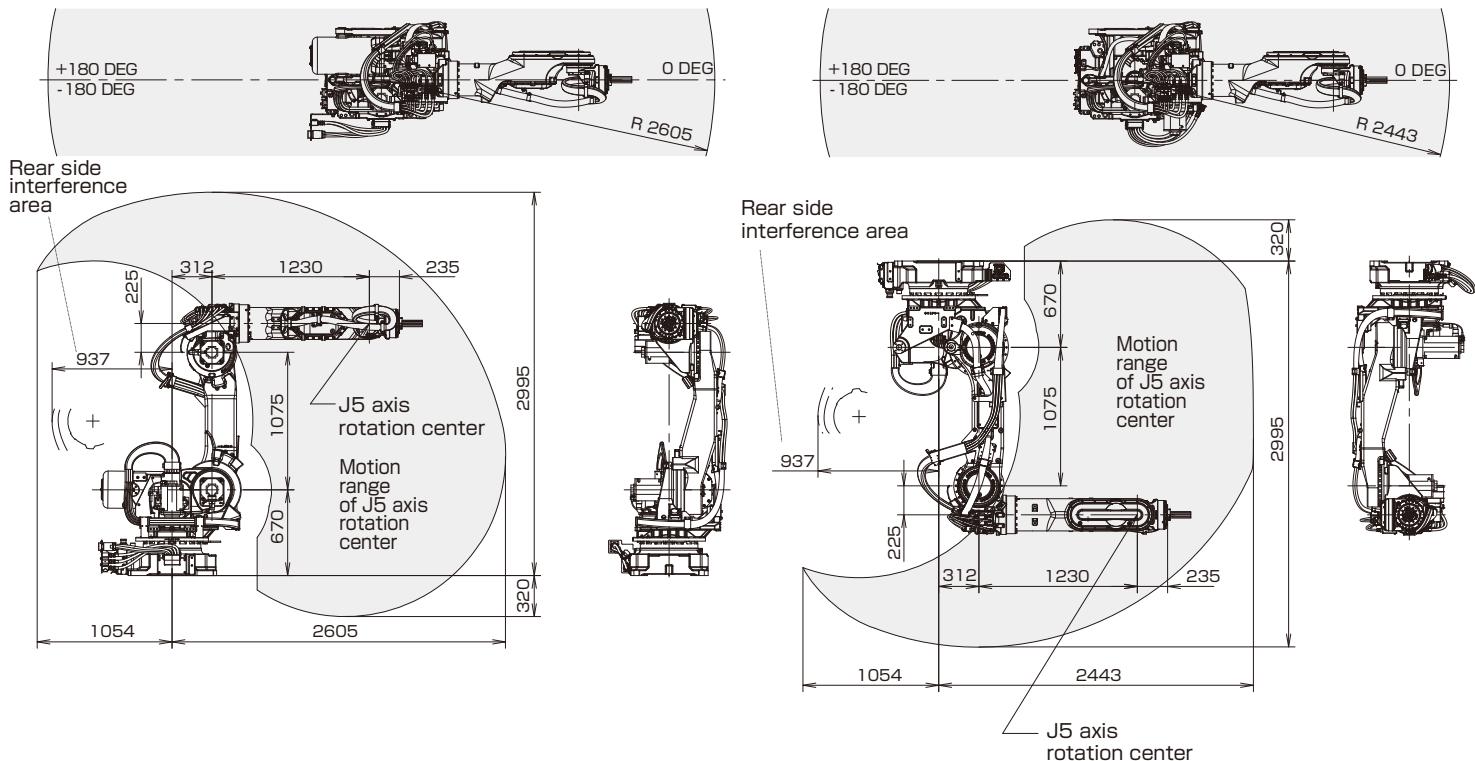
Item		Specifications	
		R-2000iB/150U	R-2000iB/220U
Type		Articulated type	
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)	
Reach		2655mm	2470mm
Installation		Upside-down	
Motion range (Maximum speed) Note 1)	J1 axis rotation	360° (110°/s) 6.28rad (1.92rad/s)	360° (95°/s) 6.28rad (1.66rad/s)
	J2 axis rotation	136° (85°/s) 2.37rad (1.48rad/s)	136° (85°/s) 2.37rad (1.48rad/s)
	J3 axis rotation	362° (110°/s) 6.32rad (1.92rad/s)	362° (95°/s) 6.32rad (1.66rad/s)
	J4 axis wrist rotation	720° (150°/s) 12.57rad (2.62rad/s)	720° (120°/s) 12.57rad (2.09rad/s)
	J5 axis wrist swing	250° (150°/s) 4.36rad (2.62rad/s)	250° (120°/s) 4.36rad (2.09rad/s)
	J6 axis wrist rotation	720° (220°/s) 12.57rad (3.84rad/s)	720° (190°/s) 12.57rad (3.32rad/s)
	Max load capacity at wrist	150kg	220kg
Max load capacity at J2 base		—	—
Max load capacity on J3 arm		10kg	25kg
Allowable load moment at wrist	J4 axis	833N · m 85kgf · m	1333N · m 136kgf · m
	J5 axis	833N · m 85kgf · m	1333N · m 136kgf · m
	J6 axis	421N · m 43kgf · m	706N · m 72kgf · m
Allowable load inertia at wrist	J4 axis	78.4kg · m <sup>2</sup> 800kgf · cm · s <sup>2</sup>	141.1kg · m <sup>2</sup> 1440kgf · cm · s <sup>2</sup>
	J5 axis	78.4kg · m <sup>2</sup> 800kgf · cm · s <sup>2</sup>	141.1kg · m <sup>2</sup> 1440kgf · cm · s <sup>2</sup>
	J6 axis	40.2kg · m <sup>2</sup> 410kgf · cm · s <sup>2</sup>	78.4kg · m <sup>2</sup> 800kgf · cm · s <sup>2</sup>
Drive method		Electric servo drive by AC servo motor	
Repeatability		±0.2mm	±0.3mm
Mass Note 2)		1070kg	1150kg
Installation environment		Ambient temperature : 0~45° C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration : 4.9m/s <sup>2</sup> (0.5G) or less	

Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.  
 Note 2) Without controller.

# FANUC Robot R-2000iB/210FS, 220US

Operating space (R-2000iB/210FS)

Operating space (R-2000iB/220US)



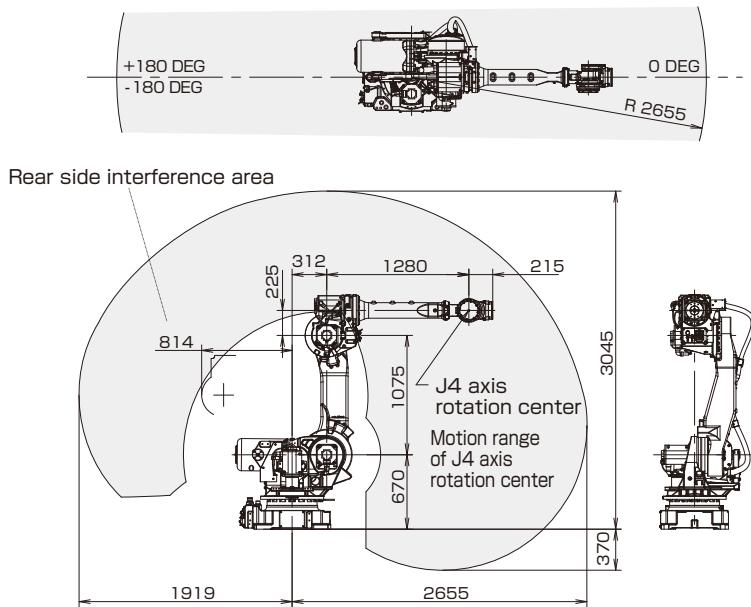
## Specifications

Item		Specifications	
		R-2000iB/210FS	R-2000iB/220US
Type		Articulated type	
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)	
Reach		2605mm	2443mm
Installation		Floor	Upside-down
Motion range (Maximum speed) Note 1)	J1 axis rotation	360° (110°/s) 6.28rad (1.92rad/s)	360° (110°/s) 6.28rad (1.92rad/s)
	J2 axis rotation	136° (90°/s) 2.37rad (1.57rad/s)	136° (85°/s) 2.37rad (1.48rad/s)
	J3 axis rotation	233.9° (95°/s) 4.08rad (1.66rad/s)	233.9° (95°/s) 4.08rad (1.66rad/s)
	J4 axis wrist rotation	420° (130°/s) 7.33rad (2.27rad/s)	420° (130°/s) 7.33rad (2.27rad/s)
	J5 axis wrist swing	250° (130°/s) 4.36rad (2.27rad/s)	250° (130°/s) 4.36rad (2.27rad/s)
	J6 axis wrist rotation	420° (200°/s) 7.33rad (3.49rad/s)	420° (200°/s) 7.33rad (3.49rad/s)
	Max load capacity at wrist	210kg	220kg
Max load capacity at J2 base		550kg	—
Max load capacity on J3 arm		—	—
Allowable load moment at wrist	J4 axis	1333N · m 136kgf · m	1333N · m 136kgf · m
	J5 axis	1333N · m 136kgf · m	1333N · m 136kgf · m
	J6 axis	706N · m 72kgf · m	706N · m 72kgf · m
Allowable load inertia at wrist	J4 axis	141.1kg · m <sup>2</sup> 1440kgf · cm · s <sup>2</sup>	141.1kg · m <sup>2</sup> 1440kgf · cm · s <sup>2</sup>
	J5 axis	141.1kg · m <sup>2</sup> 1440kgf · cm · s <sup>2</sup>	141.1kg · m <sup>2</sup> 1440kgf · cm · s <sup>2</sup>
	J6 axis	78.4kg · m <sup>2</sup> 800kgf · cm · s <sup>2</sup>	78.4kg · m <sup>2</sup> 800kgf · cm · s <sup>2</sup>
Drive method		Electric servo drive by AC servo motor	
Repeatability		±0.3mm	±0.3mm
Mass Note 2)		1250kg	1160kg
Installation environment		Ambient temperature : 0~45° C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration : Vibration acceleration : 4.9m/s <sup>2</sup> (0.5G) or less	

Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.  
 Note 2) Without controller.

# FANUC Robot R-2000iB/100H

## Operating space (R-2000iB/100H)



## Specifications

Item		Specifications R-2000iB/100H
Type		Articulated Type
Controlled axes		5 axes (J1, J2, J3, J4, J5)
Reach		2655mm
Installation		Floor
Motion range (Maximum speed) Note 1)	J1 axis rotation	360°(130°/s) 6.28rad (2.27rad/s)
	J2 axis rotation	136°(130°/s) 2.37rad (2.27rad/s)
	J3 axis rotation	362°(130°/s) 6.32rad (2.27rad/s)
	J4 axis wrist swing	250°(170°/s) 4.36rad (2.97rad/s)
	J5 axis wrist rotation	720°(360°/s) 12.57rad (6.28rad/s)
	Max load capacity at wrist	100kg
Max load capacity at J2 base		550kg
Max load capacity on J3 arm		—
Allowable load moment at wrist	J4 axis	441N·m 45kgf·m
	J5 axis	245N·m 25kgf·m
Allowable load inertia at wrist	J4 axis	39.2kg·m² 400kgf·cm·s²
	J5 axis	15.7kg·m² 160kgf·cm·s²
Drive method		Electric servo drive by AC servo motor
Repeatability		±0.2mm
Mass Note 2)		1150kg
Installation environment		Ambient temperature : 0~45° C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration : Vibration acceleration : 4.9m/s²(0.5G) or less

Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.

Note 2) Without controller.

## FANUC CORPORATION

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