THE FACTORY AUTOMATION COMPANY

FANUC .

ROBODRILL *a*-D*i*B5 series

FANUC

High-performance vertical machining centre



Automated machining for more versatile milling, drilling and tapping

Enter the efficiency zone!

FANUC designs efficiency for your production processes in the form of CNC systems, drives, robots and production machines. All produced in one of the most highly automated factories in the world. Ready to integrate and backed by unrivalled support and service. It's how we give you a competitive edge. Manufactured Efficiency for productivity to go.

Efficient products

All FANUC products involve manufactured efficiency. Fewer parts and lean technology make them reliable, predictable and easy to repair. They are made to run and provide you with the highest uptime on the market.

Efficient innovations

Manufactured efficiency is also at the heart of every FANUC innovation. Based on proven FANUC technologies, this is designed to increase the efficiency of your production facilities.

FANUC is the factory automation specialist

We've been automation experts for almost 60 years. With more than 20 million FANUC products operating worldwide – including 420,000 FANUC robots, 3.5 million FANUC CNCs and 16 million FANUC servomotors - we think our track record speaks for itself.*

Efficient support and service

FANUC support and service is about manufactured efficiency too. We listen carefully to your needs and deliver on our promises. We also take care of our products as long as they are in service. Personal and responsive, we help you achieve maximum efficiency.

Versatility beats size. Intelligence beats raw power.

The new-generation ROBODRILL promises unrivalled quality and precision at great hourly rates. With an unbeatable tool change time of 0.7 seconds and a turret capable of handling tools weighing 4 kg, the new advanced version is both the fastest and strongest vertical machining centre on the market. With by far the shortest cycle times on most machining operations, all ROBODRILL machines are real high-speed all-rounders offering incredible performance and unbeatable efficiency.

MANUFACTURED EFFICIENCY Smart is the new powerful

Using intelligent cutting strategies, ROBODRILL achieves the same results as more powerful machines in less time, regardless of whether your application involves high-speed machining, mould making or 5-axis machining.





designed and built in Japan

MANUFACTURED EFFICIENCY Future-proof investment



FANUC's legendary reliability coupled with easy preventative maintenance procedures keeps downtime to an absolute minimum. And thanks to their extreme longevity, ROBODRILL machines also provide an unbeatable return on investment.

optimal acceleration and deceleration control

latest CNC and servo technology

extraordinarily stable machining and accuracy

The multipurpose solution to your efficiency needs

Designed to meet every need, the ROBODRILL α -D*i*B5 series comprises six completely re-designed models in S, M and L sizes, available in either standard or advanced versions. With a rigid servo drive control and a highly dynamic BT30 spindle, these high-speed all-rounders are suitable for all vertical machining applications, from short production runs requiring fast turnaround times to flawless mass production. With 210,000* machines installed since 1972, its future-proof versatility and easy adaptability make the ROBODRILL the best-selling machine in its class.

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The standard version ROBODRILL α -D*i*B5 is a fast, high-quality all-rounder. With a number of different spindle options to choose from, it's perfect for standard applications. Excellent repeatability makes this model ideally suited to applications such as high-speed drilling, boring and tapping in the tooling and medical industries.

- rigid design and a rugged cast cross table
- easy maintenance thanks to direct access to all components
- easy operation thanks to quick and simple, intuitive setup options
- **new** *i***HMI** for utmost user-friendliness and full maintenance planning
- dedicated maintenance screen easy instructions ensure quick recovery if, for example, zero points are lost due to incorrect operator input
- early issue detection thanks to an integrated early warning system providing enhanced quality assurance
- **70-bar centre through coolant pressure** for non-stop deep and small diameter hole drilling
- flexibility at any time thanks to a wide range of components to suit your needs including rotary and tilting tables

ROBODRILL advanced version: extra-strong and superfast

Advanced ROBODRILL α -D*i*B5 ADV models are designed for cuttingedge high-speed machining and set the performance benchmark in their class. Providing the ultimate in precision and repeatability, they are perfect for long fully automated production runs and represent a versatile alternative to larger machines. Advanced models come with a range of highly advanced features not available on standard models.

- Additional advanced model features:
- 0.7-second tool change for superfast cycle times
- 4-kg tool handling capability for multistep tools
- 400-mm z-axis latitude for larger parts and less interference between tools and workpieces

Standard or advanced models are available in S, M and L sizes. **

ROBODRILL standard version: focus on efficiency

The secret's in the speed

Tool-on-tool changes on ROBODRILL α -D*i*B5 models are extremely fast – ranging from 0.9 seconds on our standard versions to an incredible 0.7 on the advanced. Cut to cut that means 1.5 seconds for standard and 1.3 seconds for advanced versions. That's the secret to our speed machine!

Improved swarf evacuation

the mechanism.

MANUFACTURED EFFICIENCY Stronger turret for bigger tools

Advanced model ROBODRILLs feature an even stronger turret. Offering even more versatility, this enables the tool changer to handle heavy, customised cutting tools weighing up to 4 kg while still realising ultra-quick tool changing times of 1.1 seconds.

MANUFACTURED EFFICIENCY The tool changer

At the heart of every ROBODRILL is a patented high-speed tool changer that can carry 21 tools and offers the best reliability in its class. Its manufactured efficiency lies in its solid metal construction and BIG-PLUS BBT30 spindle. This makes it extremely resistant to radial forces and enables it to deliver unbelievably efficient machining.





To maximise uptime, the ROBODRILL α -DiB5 series has been fitted with a number of swarf evacuation options: from the coolant tank and chip flush methods to a piping system for wall coolant. Advanced versions minimise swarf interference with a dome-shaped Y-axis front cover. It also offers an optional fully enclosed spindle cover that separates the machining area from













- intuitive *i*HMI screen
- easy data input and minimal keypad entry
- improved interface to robot operation screen
- precise predictive maintenance
- easy auto programming
- easy-to-use control screen
- supports multiple languages

optimised data compatibility

- Ethernet interface
- USB interface
- CF card slot









FANUC ROBODRILL for the automotive industry

Mass-producing parts for the automotive industry requires a versatile machining centre that combines speed with repeatable accuracy. It needs to keep on producing flawless parts with a minimum of downtime, accelerate quickly and deliver fast cycle times. To maximise availability and cut costs, it has to be easy to maintain and operate. On-board monitoring should make it fully predictable and ensure that preventative maintenance procedures are always focussed, timely and necessary. Given rapidly changing production runs, it needs to be quick and simple to program and set up. Doing all of this and more, ROBODRILL is ideally suited to automotive applications.

Adding fixtures

For more flexible fixture integration, the control panel is available with 220 optional PMC functions and can be customised to include dedicated buttons and lights. An additional PMC function allows operators to create their own I/O options. To ensure maximum uptime, clamping fixtures are secured automatically and the process is confirmed by sensors.

Easy automation

Thanks to a direct robot interface – for 24-h unmanned production, lower costs, easy CNC operation and communication via multiple interfaces, including PROFIBUS and FL-net.

Lower cycle times

Optimise your programs and reduce your cycle times using the latest CNC and servo control technologies such as FSSB high-speed rigid tapping, smart overlap and control time reduction.













Stable process

Measurement cycle and tool management functionality provide efficient tool monitoring for even more stable processes – absolutely reliable tool changer for seamless working in the most stable processes.



FANUC ROBODRILL for the electrical and watch industry

Electrical and watch industry applications often require tiny holes to be drilled in precision components such as disk enclosures and watch plates. To do this, ROBODRILL comes with a finely balanced spindle to ensure a very high degree of repeatable accuracy. To maximise precision on applications of this kind, ROBODRILL also includes a tool cleaning unit. Cleaning both the tool and spindle during tool changes, this feature vastly improves repeatability.

High-speed spindle

Delivering maximum precision, speed and stability, ROBODRILL's high-speed spindle is perfectly suited to the very small diameter tools used in the electrical and watch industries. Equipped with 70-bar through-spindle coolant for faster drilling and improved swarf removal, it also supports special drilling and tapping cycles for improved productivity.

HRV+ Servo Control

The HRV+ Servo Control uses high-resolution encoders and spindle control to deliver the kind of 'nano'-level surface quality demanded by the electrical and watch industries. Using smooth acceleration and deceleration to minimise axis-overshoot errors, it also decreases part-form tolerances by suppressing acceleration/deceleration delays and servo lag.

Precise drilling and tapping

On applications involving small diameter holes, peck drilling cycles and FANUC Learning Control reduce cycle times and ensure flawless continuous production.













FANUC ROBODRILL for the medical industry

Despite their complexity, medical equipment and implants often require finishing to extremely high standards. ROBODRILL comes with a number of different features designed to drastically reduce cycle times and make achieving these perfect surfaces easy. These include 5-axis functionality such as High-Speed Smooth TCP (a feature that radically improves surface quality by compensating for tool direction to avoid stripes), Tool Centre Point Control (TCP) and Tilted Working Plane.



Delivering maximum precision, speed and stability, ROBODRILL's high-speed spindle is perfectly suited to the very small diameter tools used in the medical industry. Equipped with 70-bar through-spindle coolant for faster drilling and improved swarf removal, it also supports special drilling and tapping cycles for improved productivity.

Rigid machining

Machining very hard materials often used in the medical industry, such as stainless steel and titanium, to high degrees of accuracy requires a rigid machining centre. ROBODRILL's surface table provides the enhanced rigidity this kind of machining demands – something that not only translates into maximum precision but also increased tool life.

5-axis functions (TCP/TWP)

Ideally suited to 5-axis machining operations involving two rotary axes that turn the workpiece, Smooth Tool Centre Point (TCP) provides easier programming, improved cycle time and improved quality of surface finish. This is achieved by correcting the tool orientation and smoothing the program positions. For '3+2'-axis machining, the Tilted Working Plane (TWP) function offers easy and rapid programming setup. When defining the Tilted Working Plane, an input guidance screen provides visualisation to support the operator while requesting the required data in a dialogue.











FANUC ROBODRILL for the tool making industry

Tool making necessitates high machining stability over extended periods. At the same time it's about accuracy and surface quality. FANUC ROBODRILL provides the perfect combination of high-speed precision machining and accurate, repeatable positioning. This makes it the ideal solution for high-volume applications in the mould and tool making industries. Precision is further enhanced by intelligent functions such as Nano Smoothing, High-Speed Smooth TCP or Servo Compensation.

Smoothing function

Machining functions on the FANUC CNC such as Artifical Intelligence Contour Control (AICC) and Nano Smoothing create perfectly smooth surfaces and eliminate the need for manual finishing processes on some applications. Likewise, AI Contour Control I/II enables high-precision machining at optimal machining speeds, eliminating errors, increasing feed rates and achieving perfect surfaces.

ATA Data server

Up to 4 GBs of storage for CAD/CAM programs. Files are easily transferable from a host computer to the Data Server, with part programs for multiple machines manageable from a single location, making it ideal for storing programs.

High-power machining

For heavy-duty machining operations that produce lots of swarf, such as machining moulds from hard steel blocks, a high-power version of ROBODRILL is available. Equipped with a strong spindle, rigid machine structure and excellent chip discharge, this version is also available with options to flush swarf from the wall – something that greatly extends its maintenance cycle.











HRV+ Servo Control

The HRV+ Servo Control uses high-resolution encoders and spindle control to deliver the kind of 'nano'-level surface quality demanded by the tool making industry. Using smooth acceleration and deceleration to minimise axis-overshoot errors, it also decreases part-form tolerances by suppressing acceleration/deceleration delays and servo lag.



MANUFACTURED EFFICIENCY **ROBODRILL efficiency highlights**



Versatile **5-axis** machining

To turn your ROBODRILL into a 5-axis machine, all you need to do is add the hardware. Simultaneous 5-axis control and CNC-related requirements such as indexing and simultaneous operation are already in the CNC. Intelligent options such as look-ahead data sets, interpolation and smart smoothing functions mean you can manufacture top-quality moulds, electrodes and other 3D parts quickly and precisely. That's manufactured efficiency.

Heavy-duty machining

ROBODRILL isn't just for small parts. Thanks to ROBODRILL's strong spindle and rigid structure, it is also ideally suited to heavy-duty machining applications, including high-speed operations involving lots of swarf. ROBODRILL even takes large diameter tools normally only found on bigger machines.





FANUC ROBODRILL DDR*i*B rotary table – the ideal add-on axis

Thanks to its direct drive motor and improved rigidity for more accurate machining, the FANUC ROBODRILL DDR*i*B makes the perfect additional axis for your ROBODRILL. Benefits include an indexing time of just 0.55 seconds, ultrafast clamping and a clamp torque of 700 N-m. Extremely precise and reliable, the DDR*i*B also offers unbeatable value for money.



FANUC ROBODRILL DDR-TiB the solution for parts up to 200 kg

Depending on the application, we can equip your ROBODRILL with an extremely rigid DDR-T trunnion system that features all the benefits of the DDR rotary table and includes a support spindle and L-brackets. Its improved rigidity ensures even higher degrees of machining accuracy. All you need to do is add the fixture plate. The DDR-T's practical design ensures that the existing X-axis travel remains the same as on the 3-axis design. Clamp torque on the DDR-T*i*B is 1100 N-m.



| Machining Capability | | | | | | | |
|------------------------------------|--------------------------|---|---|--|---|--|--|
| Spindle Specification Machining | | High-torq | High-torque spindle | | High-acceleration spindle High-speed spindle | | |
| | | Drilling Tool dia. (mm) × Feed (mm/rev) | Tapping Tool dia. (mm) × Feed (mm/rev) | Drilling Tool dia. (mm) × Feed (mm/rev) | Tapping Tool dia. (mm) × Feed (mm/rev) | | |
| - | Carbon Steel C45 | Dia.30 × 0.15 | M20 × 2.5 | Dia.20 × 0.10 | M16 × 2.0 | | |
| Materia | Grey Cast Iron | Dia.30 × 0.30 | M27 × 3.0 | Dia.20 × 0.25 | M22 × 2.5 | | |
| | Die Cast Aluminium Alloy | Dia.32 × 0.40 | M30 × 3.5 | Dia.22 × 0.25 | M24 × 3.0 | | |







MANUFACTURED EFFICIENCY **ROBODRILL efficiency highlights**

Remote monitoring with **ROBODRILL-LINK**i

Equipped with a new graphic interface, LINKi is an updated production and guality information management tool that allows you to monitor machine status as well as operation conditions of up to 100 ROBODRILL machines in real time from remote PCs or smart devices. Specific information is available for each machining job, and push notifications can be sent to different devices. The extremely user-friendly and intuitive interface gives you access to preventative maintenance functions as well as consumable and repair services.

Status monitor

- layout monitoring
- device monitoring/ device detail monitoring

Operation results

- group operation results
- machining results
- Diagnosis
- alarm history
- program history



Major energy savings

FANUC ROBODRILL delivers considerable energy savings compared to its larger rivals. In addition to numerous intelligent features designed to reduce energy consumption, every component has been chosen to provide the highest possible performance for the least possible energy. Power used by the servo, spindle and peripheral devices is calculated by software and displayed on the Energy Saving Screen, enabling you to monitor and optimise power consumption.



Maximum uptime

Simple maintenance - early detection: the intuitive visual maintenance interface on ROBODRILL's 31i-B5 CNC facilitates faster recoveries after servicing. The integrated early warning system identifies errors before they occur, ensuring maximum precision and consistent quality standards.





Designed for easy automation

ROBODRILL's compact design and easy accessibility from all sides make it ideally suited to trouble-free machine tending. Adding tending robots is easy thanks to our Quick & Simple Startup Packages. All FANUC products speak the same language and share a common servo and control platform – something that makes learning and operation extremely easy. For more demanding automation scenarios, FANUC's comprehensive network of dedicated European partners possesses the know-how and technical expertise you need to create the ideal solution for your production facility - no matter what your application or industry.



Standard functions



MANUAL GUIDE *i*

Designed to reduce the total time it takes you to get a drawing into production, FANUC MANUAL GUIDE *i* features an ergonomic Graphical User Interface (GUI) and user-friendly icons. Users also benefit from assisted and conversational programming of machining cycles, easy parts programming and simulation.



Quick Screen

To save you time, ROBODRILL's control panel includes four Quick Screens for fast programming and maintenance. These comprise screens for:

- quick CNC program editing
- coordinates and tool compensation settings

 including the ability to protect and restore data
- machine operation settings including machining and energy modes according to program
- maintenance settings including turret restoration and motor referencing



Machining Mode Setting Function

Using this feature, it is possible to set and optimise machining and energy modes according to the program. Servo parameters can be altered to suit machining conditions and machining mode parameters changed via M-code during machining in order to create the best possible conditions for process.



Preventive Maintenance Guidance

Offering a complete overview of ROBODRILL's leakage detection functionality, ROBODRILL's maintenance guidance screens flag up insulation resistance and power leakage issues early, thus avoiding breakdowns by indicating the need for preventative maintenance. Likewise, the screens support periodical maintenance through schedules and reminders. These processes can also be easily customised to suit your exact needs.



Custom PMC

ROBODRILL's custom PMC features easy-to-create LADDER programs for peripheral devices, including the ability to set LADDER program I/O and customise I/O signals. Its custom control panel includes the ability to monitor the status of peripheral devices, control the ON/OFF on machining programs, create ON/OFF, lamp and pulse switches. Using the panel, peripheral devices are easy and inexpensive to construct and maintain.



AI Thermal Displacement Compensation

Easy to set up, this function significantly reduces machine warm-up times and ensures accurate machining under thermal growth conditions that can affect dimensional accuracy. By monitoring the operational status of the spindle, the function adjusts the machining process to compensate for any elongation that occurs.

| List | t of standard functions |
|------|--|
| 1. | new <i>i</i> HMI |
| 2. | 10K high-torque spindle |
| 3. | basic top cover |
| 4. | LED interior lighting |
| 5. | automatic oil lubricating |
| 6. | Dual Check Safety (DCS) |
| 7. | 10.4" colour LCD dynamic graphic display |
| 8. | multiple language selection |
| 9. | alphanumeric operator's panel |
| 10. | manual pulse generator |
| 11. | data I/O interface |
| | (USB, PCMCIA, Ethernet) |
| 12. | Quick Screen (ROBODRILL HMI) |
| 13. | preventive maintenance guidance |
| 14. | external I/O function |
| 4 5 | (free I/U terminal DI16/DU16, 20 free M-codes) |
| 15. | custom PMC LADDER function |
| 10. | custom operator's panel function |
| 17. | Production counter |
| 10. | QUICK Editor |
| 17. | compensation (X/Y/Z axis) |
| 20. | machining mode setting function |
| 21. | energy saving function |
| 22. | MANUAL GUIDE i |
| 23. | program simulation |
| 24. | background editing |
| 25. | canned cycles for drilling |
| 26. | FSSB high-speed rigid tapping |
| 27. | spindle orientation (M19) |
| 28. | sub program call (M98[M198]/M99) |
| 29. | custom macro |
| 30. | optional block skip |
| 31. | high-speed skip |
| 32. | Al Contour Control |
| 33. | helical interpolation |
| 34. | coordinate system rotation (G68) |
| 35. | part program storage size 512 KB |
| | (optional up to 8 MB) |
| 36. | number of registrable programs 1000 |
| 07 | loptional up to 4000 |
| 37. | addition of workpiece coordinate system 48 pairs |
| 20 | tool offset memory C |
| 39 | HRV+ Serva Control |
| 40. | rapid traverse overlap function |

Optional functions



Additional axis interface (4/5 axes)

The standard 31*i*-B5 CNC already contains the functionality required to turn ROBODRILL into a 5-axis machine. All you need to add is the hardware and software option. Simultaneous 5-axis control capability is already in the CNC. Various third-party rotary tables can also be easily fitted to ROBODRILL using an additional servo amplifier and cable connector. On applications involving rotary tables, FANUC Tilted Working Plane Indexing also makes programming holes and pockets in tilted planes extremely easy.



Robot Interface 2

FANUC's Robot Interface 2 enables easy and inexpensive construction of a machining cell with safety issue. You can easily connect four ROBODRILLs and one ROBOT without an additional system controller – the complete control software is included in the ROBODRILL PMC. In addition, the robot controller supports an automatic side door or an automatic front door.



AI Tool Monitor

The AI Tool Monitor function monitors the load on a spindle during hole machining and, to prevent breakages, issues an alarm should load parameters be exceeded. Designed to prevent breakages and costly downtime from occurring, if a breakage does occur, this feature stops the machine automatically.



Smoothing functions

FANUC ROBODRILL'S Nano Smoothing functionality reduces the need for manual finishing on processes, such as mould machining, that require sculptured surfaces. Look-ahead blocks expansion enables higher-precision machining on processes, such as die and mould machining, that involve cutting complex part forms defined by numerous tiny program blocks. Al Contour Control I/II enables high-precision machining at optimal machining speeds, eliminating errors and increasing feed rates.



Touch probe system

For the exact measurement of tools and workpieces as well as contract-free tool breakage monitoring, ROBODRILL can be equipped with state-of-the-art touch probes and tool measurement devices from a third party.



Network interfaces

Networking ROBODRILL with personal computers and robots is achieved easily via Ethernet. ROBODRILL supports various types of field networks and connections such as I/O Link, PROFIBUS-DP and FL-net.

List of optional functions

- 1. 10K high-acceleration spindle/ 24K high-speed spindle
- 2. 70-bar centre through coolant
- 3. tooling system BIG-PLUS (BBT30)/DIN (SK30)
- 4. High Column (up to +300 mm)
- 5. additional axis interface (4 axes/5 axes)
- 6. direct drive rotary table DDR/DDR-T
- 7. various coolant options (chip flush/CT coolant/tool taper cleaning)
- 8. automatic front door and/or side door
- 9. wide opening front door (M: 730 mm/L: 1100 mm)
- 10. side window of splashguard (CE Lattice window)
- 11. chip flush improvement covers
- 12. fully closed top cover
- 13. automatic lubrication
- 14. signal lamp
- 15. tool run-out detection function
- 16. AI Tool Monitor
- 17. touch probe system (Renishaw/BLUM)
- 18. Robot Interface 2 function
- 19. network interface (Fast Ethernet, FL-net, PROFIBUS, Devicenet, I/O Link etc.)
- 20. various additional I/O modules for custom PMC function
- 21. Fast Data Server 2 GB or 4 GB
- 22. Al Contour Control II
- 23. high-speed processing and look-ahead blocks expansion (1000 blocks)
- 24. Nano Smoothing/Nano Smoothing 2
- 25. Tool Centre Point Control (TCP/High-speed Smooth TCP)
- 26. 3D cutter compensation
- 27. 3D coordinate system conversion
- 28. Tilted Working Plane Indexing command
- 29. rotary table dynamic fixture offset
- 30. NURBS Interpolation
- 31. conical/spiral interpolation
- 32. cylindrical interpolation
- 33. Polar Coordinate Command
- 34. tool position offset/scaling/ programmable mirror image
- 35. single-direction positioning
- 36. small-hole peck drilling cycle
- 37. learning control for parts cutting
- 38. tool management function for ROBODRILL
- 39. power failure backup module
- 40. more FANUC CNC hardware/software functions on request

The ROBODRILL α -D*i*B5 series comprises six completely re-designed models in S, M and L sizes, available in either standard or advanced versions.

ROBODRILL Standard version: focus on efficiency

The standard version ROBODRILL α -D*i*B5 is a fast, high-quality allrounder. With a number of different spindle options to choose from, it's perfect for standard applications. Excellent repeatability makes this model ideally suited to applications such as high-speed milling, drilling and tapping in the tooling and general industries.

ROBODRILL Advanced version: extra-strong and superfast

Advanced ROBODRILL α -D*i*B5 ADV models are designed for cutting-edge high-speed machining and set the performance benchmark in their class. Faster tool change and better chip evacuation make the Advanced version perfect for long fully automated production runs and represents a versatile alternative to larger machines. Advanced models come with a range of highly advanced features not available on standard models.

| $RODODRE \mathfrak{a}^{-} D \mathfrak{l} D \mathfrak{l} \mathfrak{d} \mathfrak{l}$ | | _ |
|---|---|---|
| Item | D <i>i</i> B series (Standard) in comparison to D <i>i</i> A series | DiBADV series (Advanced version) in comparison to DiB standard version |
| Machine's line-up structure | X axis stroke: 3 types (500 mm, 700 mm, 300 mm) Tool number: 2 types (14 tools, 21 tools) Max. control axes : 1 type [up to 5 axes] | Same as for standard D <i>i</i> B machines |
| Cycle time | Improvement of simultaneous operation of ATC with X, Y and additional axes | Improvement of simultaneous operation of ATC with X, Y and additional axes Reducing tool change time of ATC by servo turret |
| Stroke | No changes in comparison to D <i>i</i> A series Z axis stroke 330 mm | Extended Z axis stroke (from 330 to 400 mm) No change for X and Y axes stroke Increased distance from Z axis cover to center of spindle (from 380 to 418 mm) Expanded Z axis cover to lower side (from table top +179 mm to -158 mm) |
| Distance from table surface to spindle gauge plane | No changes in comparison to D <i>i</i> A series 150~480 mm (without high column option) | 80~480 mm (without high column option) |
| Mechanical section | No change for main components in comparison to D <i>i</i> A series | New design of machine structure resulting in improved Y axis travel Improved protection against chips Better chip evacuation |
| Tool turret | No changes in comparison to D <i>i</i> A series Tool to tool (2 kg setting): 0.9 sec. | Tool to tool (2 kg setting): 0.7 sec. Maximum tool mass. 4 kg Maximum tool length 250 mm on X500 and X700 with double front door option |

DiB series (Standard) Item Splashguard Changing width of machine compared to $X500: 1565 \rightarrow 1615 \text{ mm} \text{ (extend +50 mm)}$ X700: 2115 → 2165 mm (extend +50 mm) X300: No change (995 mm) No changes in comparison to DiA series **Coolant** exit Adoption New *i*HMI **Operation screen** Can use DiA series's screen on this new **Operator's Panel** New design New key layout One button for main power of ON/OFF 2 USB ports New additional button for chip flush RS232C (available as option) Program protect key removed (moved to management screen) Automatic power off button removed (setti Cabinet (back side) New wiring PCB New improved quick terminal blocks New Breaker unit Option plate for additional I/O unchanged compared to D*i*A series Options included as standard New full alphanumeric operator's panel for the European market (Former standard type is no longer availal The angle plate for LED illumination Bottom guard for improved chip evacuation **Obsolete options** I/O unit model A (horizon type) Additional I/O terminal DI16/D016 (input 4points NPN/Relay output) Additional I/O terminal DI16 (DI only) New options RS232C connection **Rapid traverse** 54 m/min **Cutting Feedrate Maximum** 30000 mm/min

ROBODRILL α -D*i*B5 series

| | DiBADV series (Advanced version) |
|----------------------|---|
| D i A series | Changing width of machine compared to D <i>i</i> A series X500: $1565 \rightarrow 1615$ mm (extend +50 mm) X700: $2115 \rightarrow 2165$ mm (extend +50 mm) X300: No change (995 mm) New excellent chip evacuation |
| | Increased height and depth No change for width |
| controller | Same as for standard D <i>i</i> B machines |
| ing on <i>i</i> HMI) | Same as for standard D <i>i</i> B machines |
| | Same as for standard D <i>i</i> B machines |
| ble) | New full alphanumeric operator's panel (former standard type is no longer available) The angle plate for LED illumination X axis telescopic cover with 3 steps (only for X500, X700) Spindle head cover (newly designed top cover) Z axis metallic cover Column cover Bed cover Redesigned telescopic cover for Y axis for better chips evacuation (only for X500, X700) Column sealing Improved protection for front door rail against chips Power failure back-up module |
| חנ | Same as for standard D <i>i</i> B machines |
| | High column 400 mm (only for X500, X700) RS232C connection |
| | Same as for standard D <i>i</i> B machines |
| | Same as for standard D <i>i</i> B machines |

Technical data standard models

α - D21S*i*B5









1900

1340

465 (100 L) 930 (200L)

245

57

α **- D21M***i*B5

1615

Π

1405 (100 L, 200 L) 1565 (240 L)

<u>68 (± 10)</u>



655

1480 J

840

L





| ROBODRILL α - D <i>i</i> B series | | α - D21S iB5 | α - D21M <i>i</i> B5 | α - D21L <i>i</i> B5 | |
|---|-------------------|------------------------|-----------------------------|----------------------|--|
| Travel X/Y/Z | mm | 300 x 300 (+100) x 330 | 500 x 400 x 330 | 700 x 400 x 330 | |
| Max. tool length (0–24,000 rpm) | mm | 190 250 | | 50 | |
| Max. tool diameter | mm | 80 | | - | |
| Table size | mm | 630 x 330 | 650 x 400 | 850 x 410 | |
| Max. table load | kg | 200 300 | | 00 | |
| Max. tool mass (0–24,000 rpm) | kg | | 3 | | |
| Distance from spindle nose to table (with HC100) | mm | | 250-580 | | |
| Controller | | | 31 <i>i</i> -B5 | | |
| Spindle speed | rqm | 10000 24000 | | | |
| Spindle load 10,000 rpm (1 min) | Nm kW | 80 14.2 | | | |
| Spindle load 10,000 rpm (continuous operation) | Nm kW | 13.6 4 | | | |
| Spindle load 24,000 rpm (1 min) | Nm kW | 35 26 | | | |
| Spindle load 24,000 rpm (continuous operation) | Nm kW | 7.5 5.5 | | | |
| Rapid traverse in all axes | m/min | 54 | | | |
| Programmable cutting feed | mm/min | 30000 | | | |
| Acceleration X/Y/Z [G] (100kg table load, 2kg-tool) | | 1.6/1.2/1.6 1.4/1.0/1. | | 1.4/1.0/1.6 | |
| Number of tools | umber of tools 21 | | 21 | 21 | |
| Tool change time (2 kg-tool) (cut to cut) | S | 1.6 | | | |
| Spindle holder BT30/SK30 DIN 69871A | | • | | | |
| Spindle holder BBT30 | | o | | | |
| Bidirectional accuracy of positioning of an axis (ISO230-2:1988) | mm | < 0.006 | | | |
| Bidirectional repeatability of positioning of an axis (ISO230-2:1997,2006) | mm | < 0.004 | | | |
| Air pressure consumption | L/min Mpa | 150 0.35–0.55 | | | |
| Machine mass/with DDR-T | | 2/2.2 | 2/2.2 | 2.1/2.3 | |



SPINDLE SPEED (MIN-1)

Spindle output 24,000 min⁻¹ (high speed)





o Optic Available

Technical data advanced models

α - D21S*i*B5adv





ل¹⁴⁸⁰ ي

α - **D21M***i***B5**ADV





α - D21L*i*B5adv





| ROBODRILL α - D <i>i</i> B ADV series | | α - D21S <i>i</i> B5adv | α - D21M iB5adv | α - D21L <i>i</i> B5adv |
|---|-------------|--------------------------------|------------------------|-------------------------|
| Travel X/Y/Z | mm | 300 x 300 (+100) x 400 | 500 x 400 x 400 | 700 x 400 x 400 |
| Max. tool length (0–24,000 rpm) | mm | 190 250 | | 50 |
| Max. tool diameter | mm | 80 | | |
| Table size | mm | 630 x 330 | 650 x 400 | 850 x 410 |
| Max. table load | kg | 200 400 | |)0 |
| Max. tool mass (0–24,000 rpm) | kg | | 4 | |
| Distance from spindle nose to table (with HC100) | mm | | 180-580 | |
| Controller | | | 31 <i>i</i> -B5 | |
| Spindle speed | rqm | 10000 24000 | | |
| Spindle load 10,000 rpm (1 min) | Nm kW | 80 14.2 | | |
| Spindle load 10,000 rpm (continuous operation) | Nm kW | 13.6 4 | | |
| Spindle load 24,000 rpm (1 min) | Nm kW | 35 26 | | |
| Spindle load 24,000 rpm (continuous operation) | Nm kW | 7.5 5.5 | | |
| Rapid traverse in all axes | m/min | 54 | | |
| Programmable cutting feed | mm/min | 30000 | | |
| Acceleration X/Y/Z [G] (100kg table load, 2kg-tool) | | 1.6/1. | 2/1.6 | 1.4/1.0/1.6 |
| Number of tools | | 21 | | |
| Tool change time (2 kg-tool) (cut to cut) | S | 1.3 | | |
| Spindle holder BT30/SK30 DIN 69871A | | • | | |
| Spindle holder BBT30 | | 0 | | |
| Bidirectional accuracy of positioning of an axis (ISO230-2:1988) | mm | < 0.006 | | |
| Bidirectional repeatability of positioning of an axis (ISO230-2:1997,2006) | mm | < 0.004 | | |
| Air pressure consumption | L/min Mpa | 150 0.35-0.55 | | |
| Machine mass/with DDR-T <i>i</i> B | | 2.2/2.4 | 2.2/2.4 | 2.3/2.5 |



SPINDLE SPEED (MIN-1)

6000

8000

10000

1700 2800

2000 4000





0 0

Spindle output 24,000 min⁻¹ (high speed)





o Optional Available

Technical tables DDR/DDR-T

| FANUC ROBODRILL DDR rotary table | Specifications |
|---------------------------------------|---|
| Drive method | Direct drive |
| Motor | Synchronous built-in servomotor DiS 260/300 |
| Continuous rating | 50 Nm |
| Maximum torque | 260 Nm |
| Table rotation speed | 200 min ⁻¹ |
| Detector | Absolute AlphaiCZ sensor 512A |
| Least input increment | 0.0001 degrees [IS-C] |
| Indexing precision | ±0.0028 degrees (±10 s) |
| Clamp method | Air pressure + spring |
| Clamp torque | 500 Nm for air pressure of 0.5 MPa |
| | 350 Nm for air pressure of 0.35 MPa |
| | 70 Nm when air pressure is shut off |
| Rotating-part inertia | J = 0.06 kgm2 (GD2 = 0.24 kgm2) |
| Permissible workpiece inertia [kg m2] | J = 0.99 kgm2 (GD2 = 3.99 kgm2) |
| Spindle outside diameter | Ø 90 mm |
| | Ø 140 mm when the end plate (option) is mounted |
| Spindle hole diameter | Ø 46 mm |
| | Ø 55 mm when the end plate (option) is mounted |
| Center height | 150 mm |
| Main body mass | 66 kg |
| Maximum loading capacity | 100 kg |
| Permissible moment load | F x L = 600 Nm |

| FANUC ROBODRILL DDR-T | X300 | X500 | X700 | | | |
|---|---------|---|--------|--|--|--|
| Clamp torque | 700 | 700 Nm (for an air pressure of 0.5 MPa) | | | | |
| Maximum Swing Ø | φ 310 | φ 310 mm | | | | |
| Number of bracket ports (option) | | 6 (oil/air) | | | | |
| Table rotation speed | | 200 min ⁻¹ | | | | |
| Maximum loading capacity | 45 kg | 100 kg | | | | |
| "Permissible workpiece inertia [Kg m²]" | J = 0.5 | J = 1.0 | | | | |
| Center height | 200 mm | 260 | mm | | | |
| Main body mass | 150 kg | 190 kg | 200 kg | | | |

DDR



Technical tables DDRiB/DDR-TiB only available for DiBADV series

| | ANUC ROBODRILL DDR <i>i</i> B rotary table |
|-----|--|
| | Drive method |
| Sy | Motor |
| | Continuous rating |
| | Maximum torque |
| | Table rotation speed |
| | Detector |
| | Least input increment |
| | Indexing precision |
| | Clamp method |
| | Clamp torque |
| | |
| | Rotating-part inertia |
| | Permissible workpiece inertia [kg m2] |
| | Spindle outside diameter |
| Ø 1 | |
| | Spindle hole diameter |
| Ø 5 | |
| | Center height |
| | Main body mass |
| | Maximum loading capacity |
| F | Permissible moment load |

| FANUC ROBODRILL DDR-T <i>i</i> B | X300 | X500 | X700 | | | |
|---|-----------------------|---|----------|--|--|--|
| Clamp torque | 1100 | 1100 Nm (for an air pressure of 0.5 MPa) | | | | |
| Maximum Swing Ø | φ 310 mm | | φ 410 mm | | | |
| Number of bracket ports (option) | 6 (oil/air) | | | | | |
| Table rotation speed | 200 min ⁻¹ | 200 min ⁻¹ l 100 min ⁻¹ l 100 min ⁻¹ | | | | |
| Maximum loading capacity | 45 kg | 100 kg l 150 kg l 200 kg | | | | |
| "Permissible workpiece inertia [Kg m²]" | J = 0.5 | J = 1.0 J = 1.5 J = 2.0 | | | | |
| Center height | 200 mm | 260 | mm | | | |
| Main body mass | 155 kg | 190 kg | 200 kg | | | |



Specifications

| Direct driveynchronous built-in servomotor $DiS 50/300$ -B46 Nm275 Nm200 min ⁻¹ 1 300 min ⁻¹ Absolute AlphaiCZ sensor 512A0.0001 degrees (IS-C) ± 0.0028 degrees (± 10 s)Air pressure + spring700 Nm for air pressure of 0.5 MPa500 Nm for air pressure of 0.35 MPa100 Nm when air pressure is shut offJ = 0.04 kgm2 [GD2 = 0.16 kgf m2]J = 1.0 kg m2 [GD2 = 4.0 kgf m2] IJ = 0.25 kg m2 [GD2 = 1.0 kgf m2]Ø 90 mm140 mm when the end plate (option) is mountedØ 46 mm55 mm when the end plate (option) is mounted150 mm80 kg100 kg I 25 kg | | 1 |
|--|---|---|
| ynchronous built-in servomotor D <i>i</i> S 50/300-B 46 Nm 275 Nm 200 min ⁻¹ I 300 min ⁻¹ Absolute Alpha <i>i</i> CZ sensor 512A 0.0001 degrees (IS-C) ± 0.0028 degrees (± 10 s) Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 1.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] I Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | Direct drive | ĺ |
| 46 Nm 275 Nm $200 \text{ min}^{-1} 1 300 \text{ min}^{-1}$ Absolute AlphaiCZ sensor 512A $0.0001 \text{ degrees (IS-C)}$ $\pm 0.0028 \text{ degrees (±10 s)}$ Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off $J = 0.04 \text{ kgm2 [GD2 = 0.16 \text{ kgf m2]}}$ $J = 1.0 \text{ kg m2 [GD2 = 4.0 \text{ kgf m2]} \text{ I}$ $J = 0.25 \text{ kg m2 [GD2 = 1.0 \text{ kgf m2]}$ 0 90 mm 140 mm when the end plate (option) is mounted 0 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg $100 \text{ kg I 25 \text{ kg}$ | ynchronous built-in servomotor D <i>i</i> S 50/300-B | ĺ |
| 275 Nm $200 \text{ min}^{-1} 1 300 \text{ min}^{-1}$ Absolute AlphaiCZ sensor 512A $0.0001 \text{ degrees [IS-C]}$ $\pm 0.0028 \text{ degrees } [\pm 10 \text{ s}]$ Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off $J = 0.04 \text{ kgm2 [GD2 = 0.16 \text{ kgf m2]}}$ $J = 1.0 \text{ kg m2 [GD2 = 4.0 \text{ kgf m2]} 1$ $J = 0.25 \text{ kg m2 [GD2 = 1.0 \text{ kgf m2]}}$ $\emptyset 90 \text{ mm}$ 140 mm when the end plate (option) is mounted $\emptyset 46 \text{ mm}$ 55 mm when the end plate (option) is mounted 150 mm 80 kg $100 \text{ kg 25 \text{ kg}}$ | 46 Nm | ĺ |
| 200 min ⁻¹ 1 300 min ⁻¹ Absolute AlphaiCZ sensor 512A 0.0001 degrees (IS-C) ±0.0028 degrees (±10 s) Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | 275 Nm | ĺ |
| Absolute Alpha/CZ sensor 512A 0.0001 degrees [IS-C] ±0.0028 degrees [±10 s] Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate [option] is mounted Ø 46 mm 55 mm when the end plate [option] is mounted 150 mm 80 kg 100 kg I 25 kg | 200 min ⁻¹ I 300 min ⁻¹ | l |
| 0.0001 degrees (IS-C) ±0.0028 degrees (±10 s) Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | Absolute AlphaiCZ sensor 512A | l |
| ±0.0028 degrees (±10 s) Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | 0.0001 degrees (IS-C) | l |
| Air pressure + spring 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | ±0.0028 degrees (±10 s) | ļ |
| 700 Nm for air pressure of 0.5 MPa 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | Air pressure + spring | ļ |
| 500 Nm for air pressure of 0.35 MPa 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | 700 Nm for air pressure of 0.5 MPa | |
| 100 Nm when air pressure is shut off J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg 25 kg | 500 Nm for air pressure of 0.35 MPa | |
| J = 0.04 kgm2 [GD2 = 0.16 kgf m2] J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | 100 Nm when air pressure is shut off | |
| J = 1.0 kg m2 [GD2 = 4.0 kgf m2] I J = 0.25 kg m2 [GD2 = 1.0 kgf m2] Ø 90 mm I40 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | J = 0.04 kgm2 [GD2 = 0.16 kgf m2] | |
| Ø 90 mm 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg I 25 kg | J = 1.0 kg m2 [GD2 = 4.0 kgf m2] J = 0.25 kg m2 [GD2 = 1.0 kgf m2] | |
| 140 mm when the end plate (option) is mounted Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg 25 kg | Ø 90 mm | • |
| Ø 46 mm 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg 25 kg | 40 mm when the end plate (option) is mounted | • |
| 55 mm when the end plate (option) is mounted 150 mm 80 kg 100 kg 25 kg | Ø 46 mm | ſ |
| 150 mm 80 kg 100 kg 25 kg | 55 mm when the end plate (option) is mounted | İ |
| 80 kg 100 kg 25 kg | 150 mm | ĺ |
| 100 kg l 25 kg | 80 kg | İ |
| | 100 kg l 25 kg | ĺ |
| | | ĺ |

F x L = 600 Nm



Efficient FANUC service worldwide

Wherever you need us, our comprehensive FANUC network provides sales, support and customer service all around the world. That way, you can be sure you have always got a local contact that speaks your language.

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